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APPLICATION NO.	FILING DATE	FIRST NAMED INVENTOR	ATTORNEY DOCKET NO.	CONFIRMATION NO.
10/529,735	03/30/2005	Gavriel J. Iddan	P-4409-US	1893
49443	7590	11/24/2009	EXAMINER	
Pearl Cohen Zedek Latzer, LLP			TOWA, RENE T	
1500 Broadway			ART UNIT	
12th Floor			PAPER NUMBER	
New York, NY 10036			3736	
			MAIL DATE	DELIVERY MODE
			11/24/2009	PAPER

Please find below and/or attached an Office communication concerning this application or proceeding.

The time period for reply, if any, is set in the attached communication.

DETAILED ACTION

1. This Office action is responsive to an amendment filed July 15, 2009. Claims 1-12, 14-15, 18, 24-30, 32-33, 36, 38-40, 43, 45-48 and 50 are pending. Claims 1, 6, 14-15, 18, 32-33, 36, 38-39, 43 & 45 have been amended. Claims 13, 16-17, 19-23, 31, 34-35, 37, 41-42, 44 and 49 have been cancelled.

Claim Objections

2. The objections are withdrawn due to amendments.

Double Patenting

3. The rejection is withdrawn due to arguments.

Claim Rejections - 35 USC § 103

4. The text of those sections of Title 35, U.S. Code not included in this action can be found in a prior Office action.

5. **Claims 1, 3, 7, 10-12, 14, 24-30, 32, 36, 40, 43-48 & 50** are rejected under 35 U.S.C. 103(a) as being unpatentable over Mullick et al. (US 2003/0167000) in view of Canton (US 6,145,393).

Mullick et al. disclose an in-vivo sensing system comprising:

- (a) a housing 42 (see figs. 2 & 3A-B; par 0055-0056);
wherein the housing 42 has a capsule shape (see figs. 2 & 3A-B);
wherein the housing is at least partially transparent (i.e. "transparent window 62") (see fig. 2);
- (b) a sensing device 48 (see par 0059);
wherein the sensing device includes an imaging device (see par 0059);

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- (c) a transmitter 50 (see par 0062); and,
- (d) a ballast weight (see par 0019; par 0065);

The Examiner notes that Mullick et al. teach an in-vivo sensing system that "may be weighted in such a way as to maintain a particular orientation in the stomach" (see par 0019); Mullick et al. further teaches that the ballast weight may be the power source or battery 54 to orient the in-vivo sensing system in the stomach (see par 0065);

Mullick et al. further teach a method for sensing an in-vivo site (see par 0018) comprising the steps of:

- (i) enabling an in-vivo sensing system 40 disposed within a housing 42 to be moved within the anatomy of a patient (see par 0055); wherein the in-vivo sensing system 40 includes an imaging device 48 (see par 0059);
- (ii) applying an external force (i.e. "gravitational force") to the in-vivo sensing system 40; wherein applying an external force includes repositioning the patient;

The Examiner notes that Mullick et al. teach an in-vivo system that performs diagnostic operations within the stomach of a patient while the patient performs activities of daily living (see par 0015) for a maximum of 72 hours (see par 0020); as such, both the patient and the in-vivo system are inherently subject to the gravitational force while the patient repositions while conducting the activities of daily living.

- (iii) transmitting data from the in-vivo sensing system 40 (see par 0019); and,
- (iv) reviewing data the transmitted data (see par 0021); and,

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- (v) applying an external force to change the direction of the imaging device 48 (i.e. “controlled mobility”) based on the reviewed transmitted data (see par 0087).

The Examiner notes that Mullick et al. teach an in-vivo system comprising an imaging system that tracks the position of the in-vivo system (see par 0061); wherein an operator can externally “re-orient” the imaging system thereof (see par 0087). As such, the Examiner submits that Mullick et al. inherently applies an external force to change the direction of imaging device based on the reviewed data (i.e. the reviewed data may only pertain to the position and/or orientation of the in-vivo capsule, which may then be “re-oriented” externally by a physician).

Mullick et al. teach an in-vivo sensing system, as described above, that fails to explicitly teach an optical stabilization platform comprising at least one friction reducing mechanism or liquid, at least one ballast weight or at least one directional activator.

However, **Canton** discloses a sensing device comprising an optical platform including:

- (a) a housing 16 (see fig. 10) comprising:
 - (b) at least one friction reducing mechanism 18 disposed between the housing 16 and a sensing device 17 (see fig. 10);
 - wherein the friction-reducing mechanism 18 includes a liquid;
 - wherein the liquid 18 has a diffraction coefficient substantially similar to a diffraction coefficient of the housing 16;
 - wherein the liquid 18 is at least partially transparent;
 - wherein the liquid is oil (see; at least one friction reducing mechanism 18;

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wherein the friction-reducing mechanism 18 includes a liquid;

wherein the liquid 18 has a diffraction coefficient substantially similar to a diffraction coefficient of the housing 16;

wherein the liquid 18 is at least partially transparent;

wherein the liquid is oil (see col. 4, lines 52-65);

(c) a sensing device 17 (see fig. 10);

wherein the sensing device 17 has a weight that is evenly distributed along a horizontal and a vertical axis of the sensing device 17 (see col. 4, lines 16-20);

wherein the sensing device 17 has a specific gravity that does not substantially exceed the specific gravity of the liquid 18 (see col. 4, lines 6-8);

wherein the liquid 18 is introduced into the housing 16 during use (col. 6, lines 19-24, 31-42 & 51-57);

wherein the sensing device 17 includes an imaging device 20 (see col. 8, lines 14-15);

wherein the imaging device 20 includes a ballast weight (see col. 4, lines 20-31);

(d) at least one directional activator (17B) attached to said sensing device 17 (see fig. 10);

wherein the directional activator 17B comprises at least one magnet (17B) (see col. 7, lines 1-10); and,

(e) at least one directional actuator 17A external to said housing 16 to control said at least one directional actuator 17B; wherein the at least one actuator is magnetic field generator (see col. 7, lines 1-10).

The Examiner notes that Canton teaches a device wherein a first set of electromagnets 17A are positioned on the outer vessel 16 (housing) and a second inner set electromagnets 17B are positioned on the inner vessel assembly 17 (sensing device) such that, using magnetic deflection or attraction approach, as directed by microprocessor 29, are selectively turned on and off to cause the inner vessel 17 (sensing device) to rotate, to realign viewing port 23 with viewing port 19; as such, the Examiner submits that the first set of electromagnets 17A serves as an actuator in that it can be turned on and off to cause the inner vessel 17 to rotate. For example, in order to cause "magnetic deflection/attraction," the electromagnets 17A inherently generate an electrical field when turned on.

In regards to **claims 1, 3, 7, 10, 14, 24-26, 30, 32, 36, 40, 43-48 & 50**, Mullick et al. teach a vehicular in-vivo system that can include a machined mechanical stabilization platform that can be built into the imaging system to stabilize the image (see par 0087); since Canton teaches a sensing device having a stabilization platform for stabilizing images (see col. 1, lines 8-10) that could be mounted on a vehicular device (see col. 3, lines 44-48), it would have been obvious to one of ordinary skill in the art at the time Applicant's invention was made to provide the system of Mullick et al. with an optical platform having a friction reducing mechanism as taught by Canton in order to achieve an in-vivo system having an imaging device that is able to float in neutral buoyancy thereby stabilizing images recorded by the moving imaging device.

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Similarly, Mullick et al. teach an image stabilization system that includes miniature motors to allow the imaging system to be reoriented (see par 0087); since Canton teaches a pair of magnets for repositioning the imaging device 20 with respect to the viewing port 23 (see fig. 10; col. 7, lines 1-10), it would have been obvious to one of ordinary skill in the art at the time Applicant's invention was made to provide the system of Mullick et al. with at least one directional activator (electromagnets 17B) and at least one directional actuator (electromagnets 17A) as taught by Canton in order to selectively reorient the imaging device. Furthermore, although Canton teaches at least one activator 17B that is attached to the external surface of the sensing device 17 (see fig. 10), it would have been obvious to one of ordinary skill in the art at the time Applicant's invention was made to provide the system of Mullick et al. as modified by Canton above with at least one activator that is located within the sensing device as claimed since such a modification would serve the same purpose of attaching the at least one activator to the sensing device so as to be able to selectively reorient the imaging device.

Similarly, in regards to **claims 11-12**, Mullick et al. teach an in-vivo system that includes a ballast to orient the capsule in the stomach (see par 0065); since Canton teaches a sensing device having a weight that is evenly distributed along a horizontal and vertical axis of the sensing device (see col. 4, lines 16-20 & 29-32), it would have been obvious to one of ordinary skill in the art at the time Applicant's invention was made to provide the system of Mullick et al. with a weight that is evenly distributed along a horizontal and vertical axis as taught by Canton in order to position the imaging device

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at the physical center of the system so as to achieve an imaging device that will not occur if acceleration forces are applied to the system.

In regards to **claim 27**, Mullick et al. teach an in-vivo sensing device that allows the in-vivo sensing device (i.e. "imaging system") to be reoriented, which could include a remote control (see par 0087); since Canton teaches a sensing device that can become misaligned with viewing port 19 of the housing 16 (see col. 5, lines 1-7) such that a pump 29 would thrust the friction reducing liquid 18 into the housing 16 to correct the misalignment or orient the sensing device 20 to observe through any portion of the hemisphere of the viewing port 19 of the housing 16 (see col. 6, lines 5-11, 19-24, 31-42 & 51-57), it would have been obvious to one of ordinary skill in the art at the time Applicant's invention was made to provide the system of Mullick et al. with a liquid that is introduced during use as taught by Canton in order to correct any misalignment occurring during use or to orient the sensing device to observe through any portion of the hemisphere of the viewing port.

In regards to **claims 28-29**, since Canton teaches a sensing device wherein the liquid has similar optical properties as the viewing port 19 of the housing 16 so that the liquid must also be transparent (i.e. similar diffraction coefficient of the housing) to the wavelengths of light required by the imaging system (see col. 4, lines 56-65), it would have been obvious to one of ordinary skill in the art at the time Applicant's invention was made to provide the system of Mullick et al. with a liquid having a diffraction coefficient that is substantially to a diffraction coefficient of the housing as taught by Canton in

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order to allow the liquid and the housing to be transparent to the wavelengths of light required by the imaging system.

6. **Claim 2** is rejected under 35 U.S.C. 103(a) as being unpatentable over Mullick et al. ('000) in view of Canton ('393), and further in view of Von Alten (US 6,929,636).

Mullick et al. as modified by Canton disclose an in-vivo system, as described above, that fails to explicitly teach a housing that includes a material consisting of glass, plastic or rubber.

However, **Von Alten** teaches an in-vivo system comprising an inert housing that includes a material consisting of glass (see figs. 1-2; col. 5, lines 27-30).

It would have been obvious to one of ordinary skill in the art at the time Applicant's invention was made to provide the system of Mullick et al. as modified by Canton with a housing that includes glass as taught by Von Alten in order to achieve a housing that is inert or biocompatible in the human body.

7. **Claim 4** is rejected under 35 U.S.C. 103(a) as being unpatentable over Mullick et al. ('000) in view of Canton ('393), and further in view of Bucalo (US 4,172,446).

Mullick et al. as modified by Canton disclose an in-vivo system, as described above, that fails to explicitly teach a collapsible housing.

However, **Bucalo** discloses an in-vivo system comprising a collapsible housing 20 (see fig. 1; col. 3, lines 40-60).

Mullick et al. teach an in-vivo system comprising a suction port 500 to remove unwanted debris from the gastrointestinal tract to improve or enhance visualization, diagnostic, therapeutic or other functions of the capsule (see fig. 12; par 0082); since

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Bucalo teaches an in-vivo system comprising a pre-collapsed housing for generating suction in-vivo based on a condition prevailing in the body cavity (see col. 3, lines 40-60), it would have been obvious to one of ordinary skill in the art at the time Applicant's invention was made to provide the system of Mullick et al. as modified by Canton with a collapsible housing as taught by Bucalo in order to achieve a suction generating mechanism that is activated based on a condition prevailing in the body cavity in-vivo to improve or enhance visualization, diagnostic or therapeutic functions of the in-vivo system.

8. **Claim 5** is rejected under 35 U.S.C. 103(a) as being unpatentable over Mullick et al. ('000) in view of Canton ('393), Bucalo ('446) and further in view of Kovacs et al. (US 5,833,603).

Mullick et al. as modified by Canton and Bucalo disclose an in-vivo system, as described above, that fails to explicitly teach a semi-permeable housing.

However, **Kovacs et al.** disclose an in-vivo system comprising a housing 126 that is collapsible and semi-permeable (see figs. 10-11; col. 15, lines 25-49).

It would have been obvious to one of ordinary skill in the art at the time Applicant's invention was made to provide the system of Mullick et al. as modified by Canton and Bucalo with a semi-permeable membrane as taught by Kovacs et al. in order to achieve an ion-selective selective chemical sensor using an electrochemical measurement such as impedance, spectroscopy, voltammetry, and amperometry.

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9. **Claims 6, 8-9, 18, 33 & 38-39** are rejected under 35 U.S.C. 103(a) as being unpatentable over Mullick et al. ('000) in view of Canton ('393), and further in view of Kilcoyne et al. (US 6,285,897).

Mullick et al. as modified by Canton disclose an in-vivo system, as described above, that fails to explicitly teach an attachment mechanism or a pH sensor.

However, **Kilcoyne et al.** disclose an in-vivo system (see col. 3, lines 6-10) comprising:

(a) a housing 120:

wherein the housing 120 is an inert hydrocarbon (i.e. polyethylene) (see col. 6, lines 55-62);

(b) an attachment mechanism (see fig. 6) comprising anchors or fasteners such as tacks, pins, hooks, barbs, sutures, clips, staples (see col. 9, lines 5-51) or glue such as an adhesive (see col. 8, lines 48-60); and,

(c) at least one sensor (i.e. pH, temperature or pressure sensor) (see col. 5, lines 15-46).

In regards to **claim 6**, it would have been obvious to one of ordinary skill in the art at the time Applicant's invention was made to provide the system of Mullick et al. as modified by Canton with a housing that includes a hydrocarbon as taught by Kilcoyne et al. in order to achieve a housing that is inert or biocompatible in the human body.

In regards to **claims 8-9 & 33**, Mullick et al. teach an in-vivo system comprising a plurality of retractable prongs 180 to effectively anchor or stabilize the in-vivo system (see fig. 8; par 0073); since Kilcoyne et al. teach other means for effectively anchoring

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an in-vivo system in the gastrointestinal track of a patient (see fig. 6), it would have been obvious to one of ordinary skill in the art at the time Applicant's invention was made to provide the system of Mullick et al. as modified by Canton with an attachment mechanism as taught by Kilcoyne et al. in order to temporarily attach, anchor or stabilize the in-vivo device to the body lumen so as to collect physiological data therefrom.

In regards to **claims 18 & 38-39**, similarly, it would have been obvious to one of ordinary skill in the art at the time Applicant's invention was made to provide the system of Mullick et al. as modified by Canton with a pH sensor as taught by Kilcoyne et al. in order to achieve long-term monitoring of gastroesophageal reflux (GERD).

10. **Claim 15** is rejected under 35 U.S.C. 103(a) as being unpatentable over Mullick et al. ('000) in view of Canton ('393), and further in view of DiCarlo (US 2003/0004562).

Mullick et al. as modified by Canton disclose an in-vivo system, as described above, that fails to explicitly teach a magnetic switch.

However, **DiCarlo** discloses an in-vivo sensing system (see par 0030) comprising a remote-activatable magnetic switch 34 (see fig. 2; par 0032-0033).

Since Mullick et al. teach an in-vivo sensing device that allows the in-vivo sensing device (i.e. "imaging system") to be reoriented, which could include a remote control (see par 0087) and Canton teaches a sensing device that can be selectively repositioned or rotated using a set of electromagnets magnetic (see fig. 10; col. 7, lines 1-10), it would have been obvious to one of ordinary skill in the art at the time Applicant's invention was made to provide the system of Mullick et al. as modified by

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Canton with a magnetic switch as taught by DiCarlo in order to achieve an in-vivo sensing device that can selectively be reoriented remotely; for example, similar to Mullick et al., Canton teaches a sensing device 20 that can be pointed to observe through any portion of the hemisphere of the viewing port 19 (see fig. 10; col. 6, lines 51-57); as such, the magnetic switch 34 of DiCarlo may serve as means to override to the microprocessor 29, which is mainly concerned with realignment of the viewing ports (23, 29), in order to point the sensing device 20 to observe through any portion of the hemisphere of the viewing port 19.

Response to Arguments

11. Applicant's arguments filed September 15, 2009 have been fully considered but they are not persuasive. Applicant argues that Canton fails to teach at least one directional activator and at least one directional actuator that comprises a magnetic field generator. This argument has been considered but has been deemed persuasive.

In response to the Applicant's response, the Examiner respectfully traverses. The Examiner notes that Canton teaches a device wherein a first set of electromagnets 17A are positioned on the outer vessel 16 (housing) and a second inner set electromagnets 17B are positioned on the inner vessel assembly 17 (sensing device) such that, using magnetic deflection or attraction approach, as directed by microprocessor 29, are selectively turned on and off to cause the inner vessel 17 (sensing device) to rotate, to realign viewing port 23 with viewing port 19; as such, the Examiner submits that the first set of electromagnets 17A serves as an actuator in that it can be turned on and off to cause the inner vessel 17 to rotate. For example, in order to cause "magnetic

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deflection/attraction," the electromagnets 17A inherently generate an electrical field when turned on.

In view of the foregoing, the rejections over Canton are maintained.

Conclusion

12. Applicant's amendment necessitated the new ground(s) of rejection presented in this Office action. Accordingly, **THIS ACTION IS MADE FINAL**. See MPEP § 706.07(a). Applicant is reminded of the extension of time policy as set forth in 37 CFR 1.136(a).

A shortened statutory period for reply to this final action is set to expire THREE MONTHS from the mailing date of this action. In the event a first reply is filed within TWO MONTHS of the mailing date of this final action and the advisory action is not mailed until after the end of the THREE-MONTH shortened statutory period, then the shortened statutory period will expire on the date the advisory action is mailed, and any extension fee pursuant to 37 CFR 1.136(a) will be calculated from the mailing date of the advisory action. In no event, however, will the statutory period for reply expire later than SIX MONTHS from the date of this final action.

13. Any inquiry concerning this communication or earlier communications from the examiner should be directed to RENE TOWA whose telephone number is (571)272-8758. The examiner can normally be reached on M-F, 2:00PM-10:00PM.

If attempts to reach the examiner by telephone are unsuccessful, the examiner's supervisor, Max Hindenburg can be reached on (571) 272-4726. The fax phone

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number for the organization where this application or proceeding is assigned is 571-273-8300.

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/Rene Towa/
Examiner, Art Unit 3736

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Supervisory Patent Examiner, Art Unit 3736